

Proc Art

FIG. (

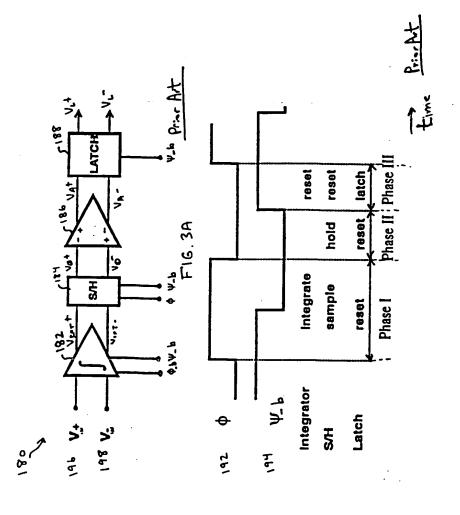


FIG. 3B

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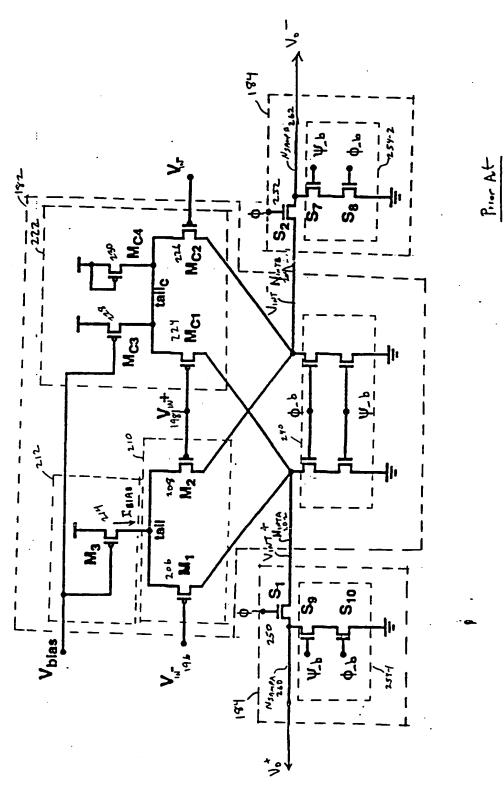


FIG. 4

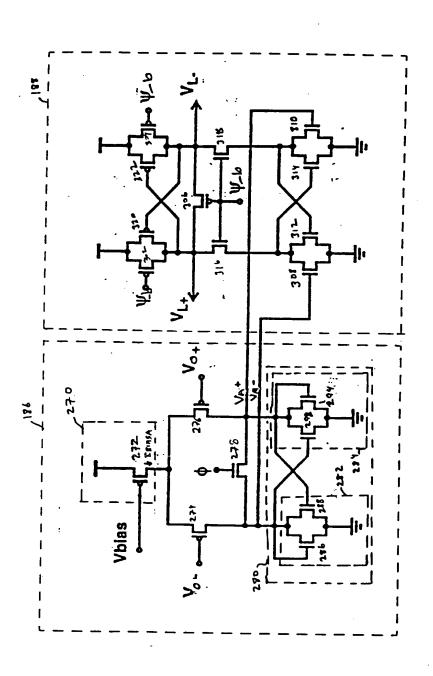
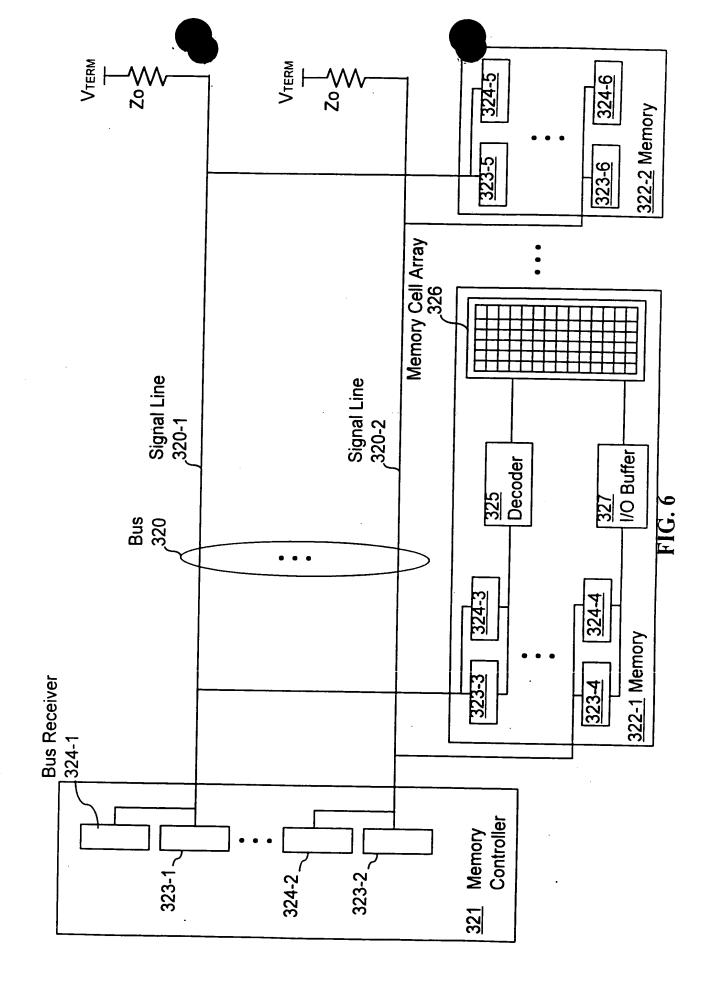


FIG. 5

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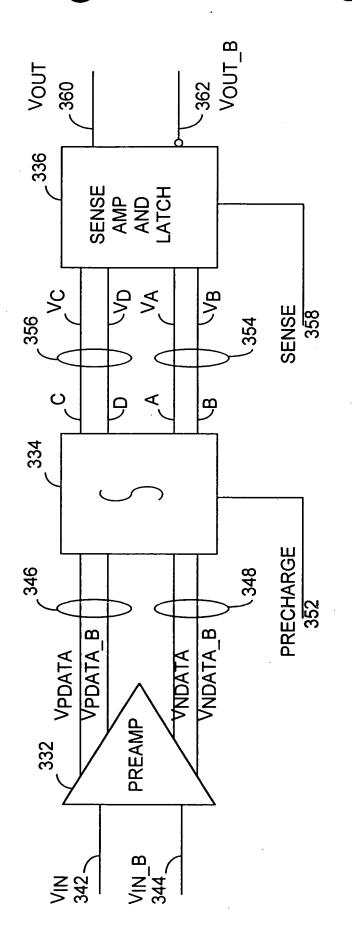
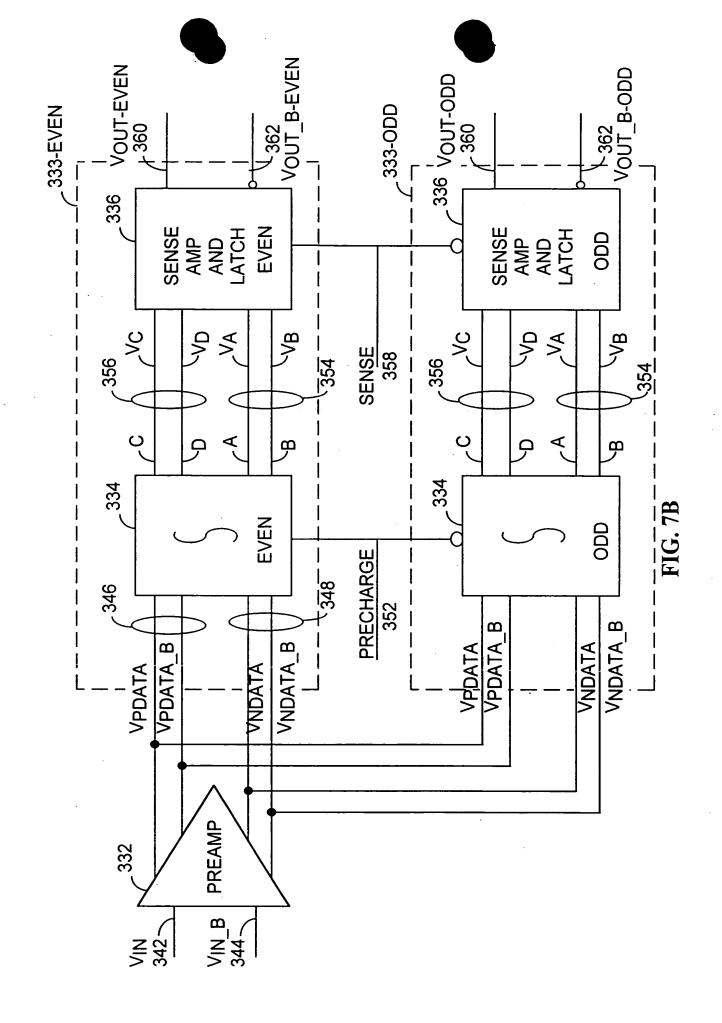
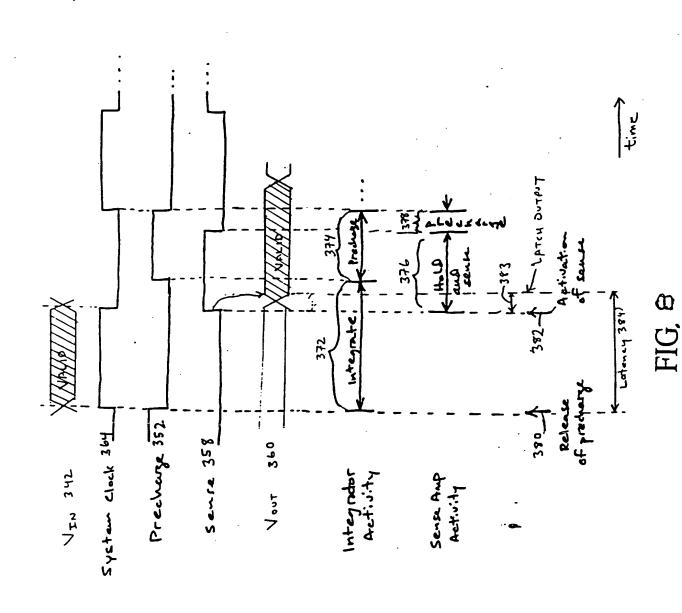


FIG. 7A



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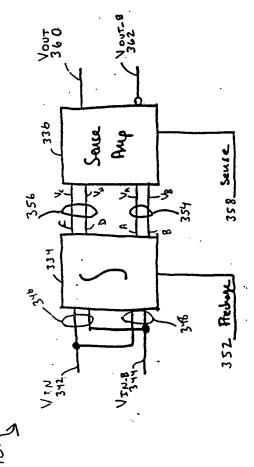


FIG. o

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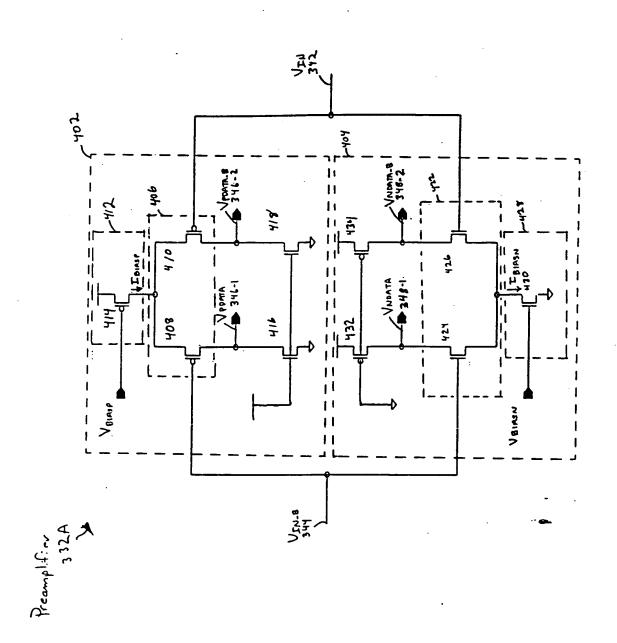


FIG 10



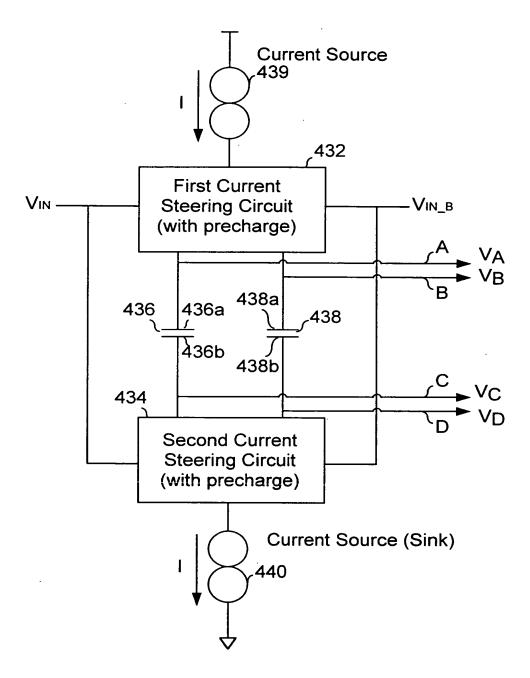


FIG. 11A

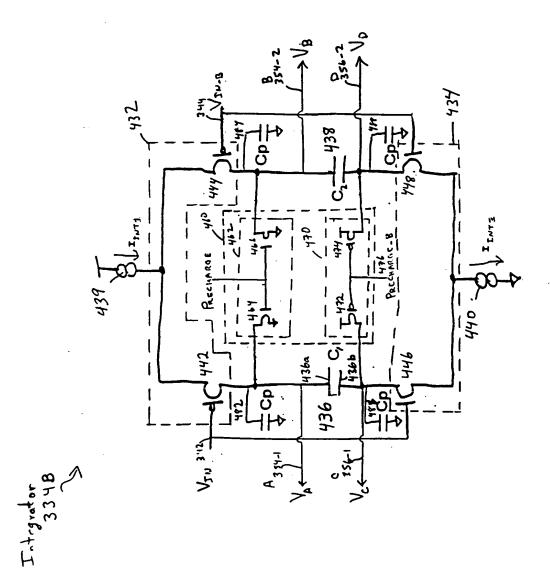


FIG. 11B

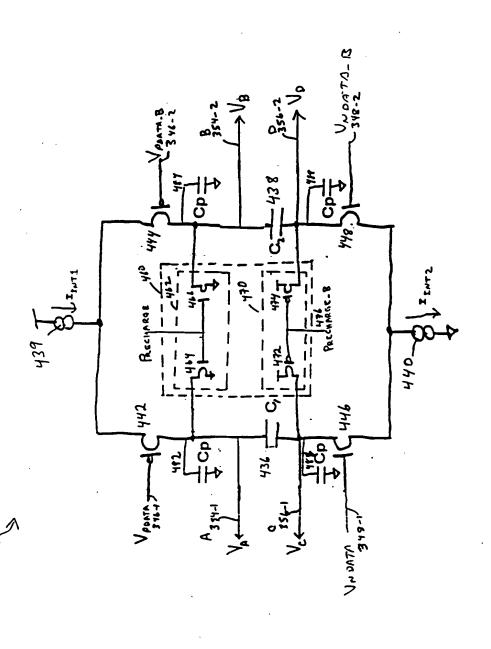


FIG. 11 c

بر :

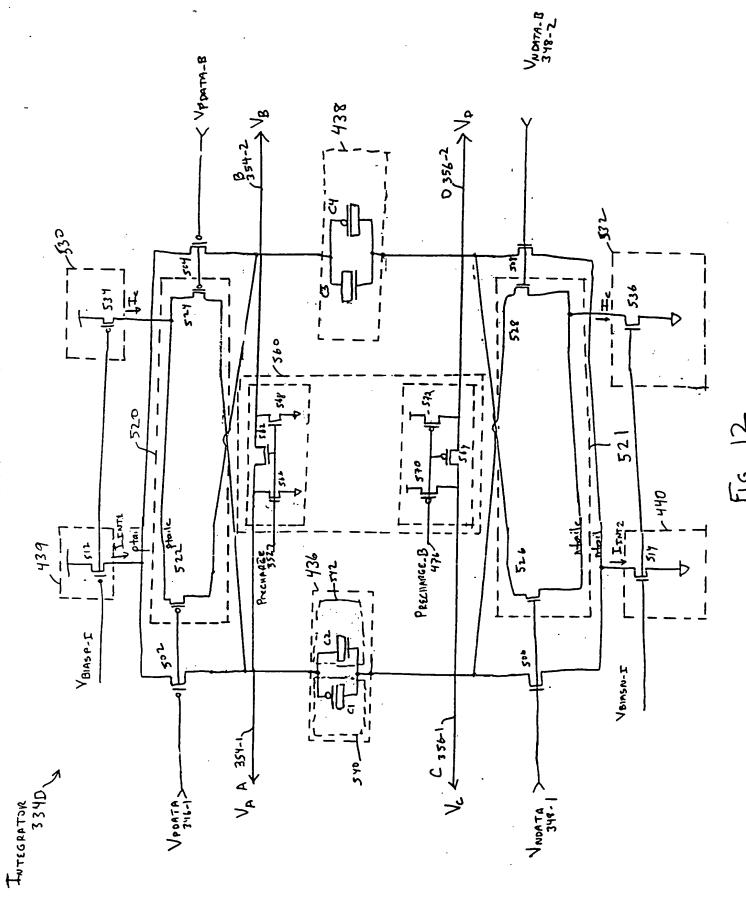


Fig. 12

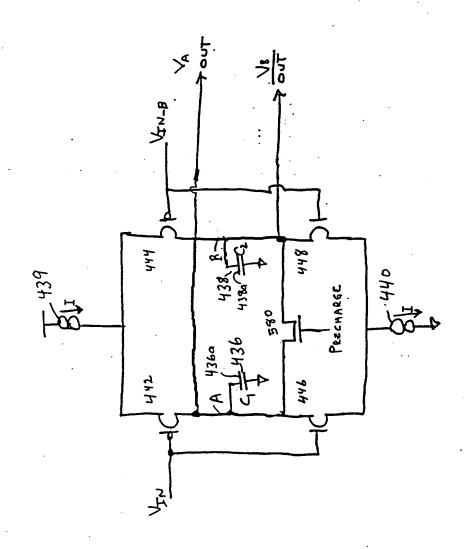
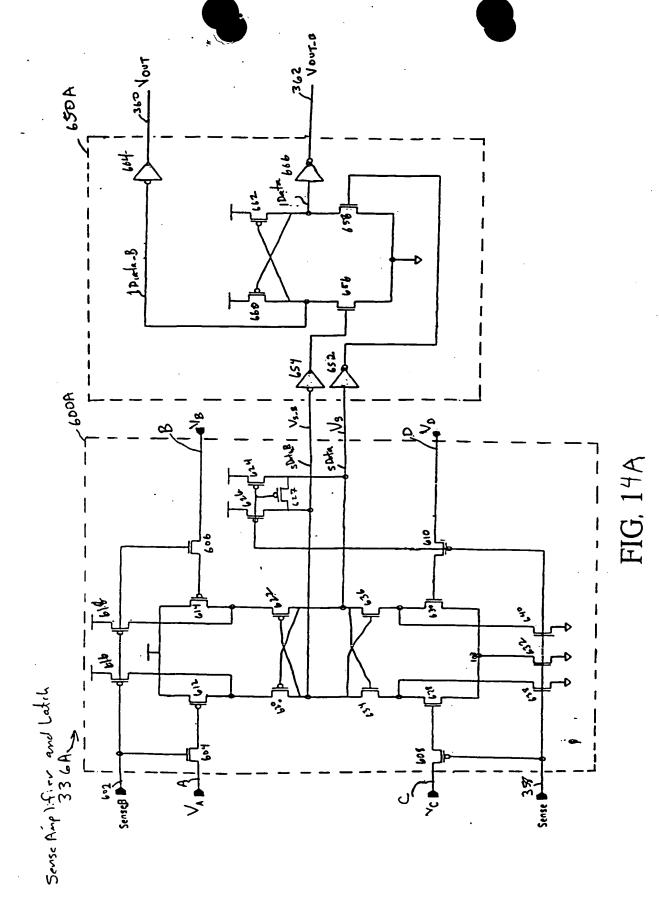
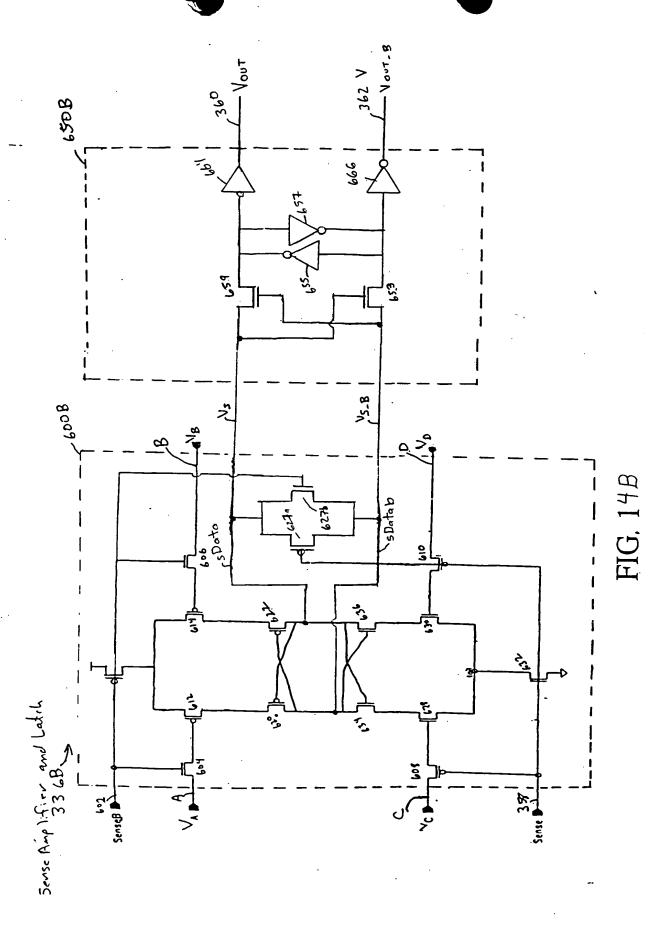
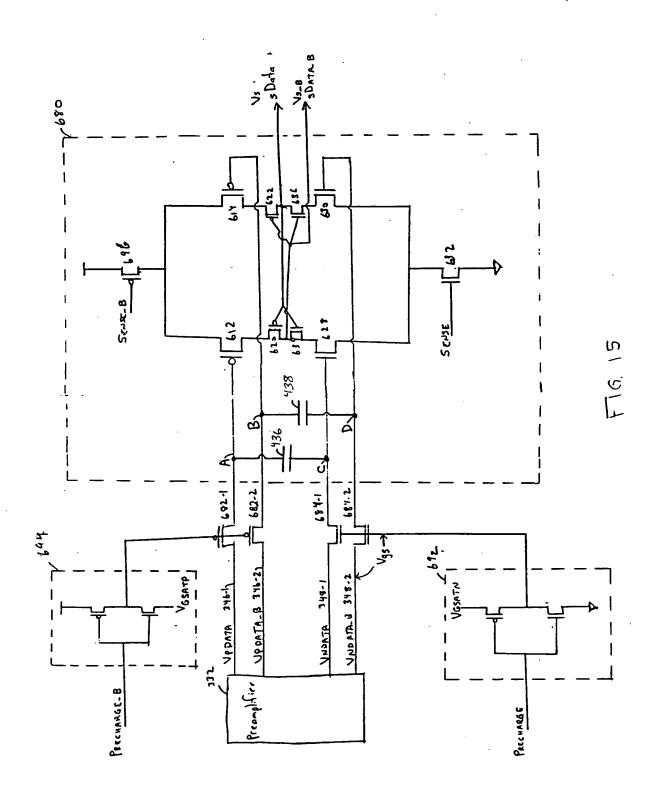


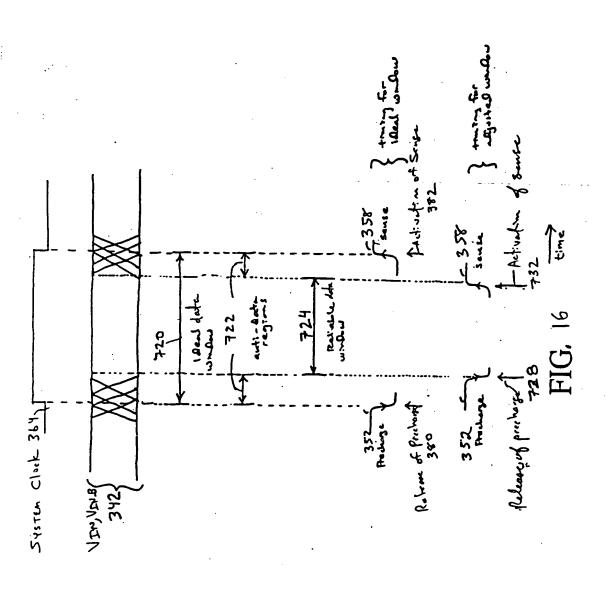
FIG. 13

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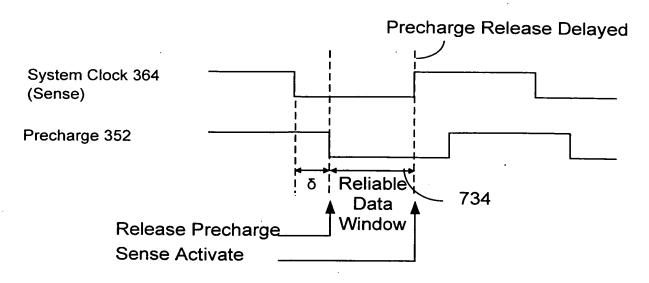


FIG. 17A

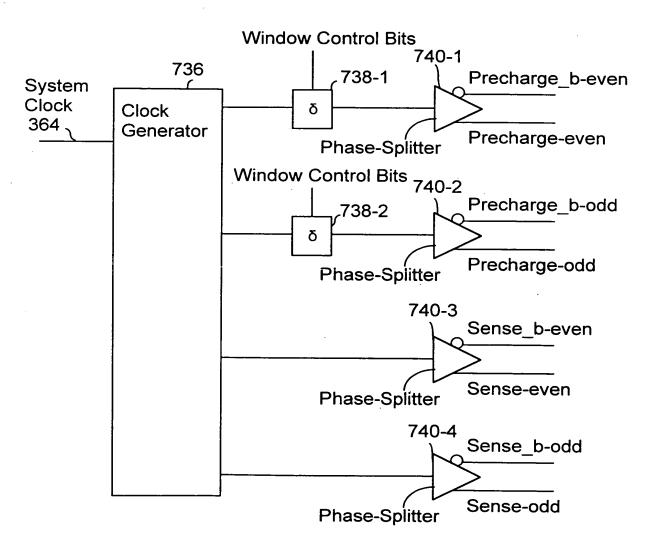
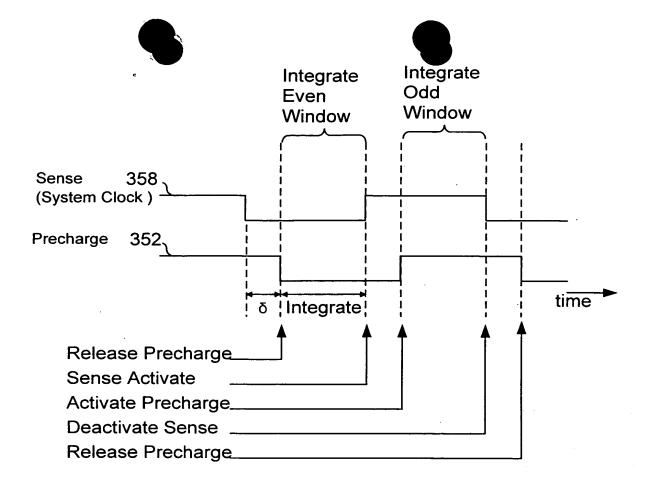
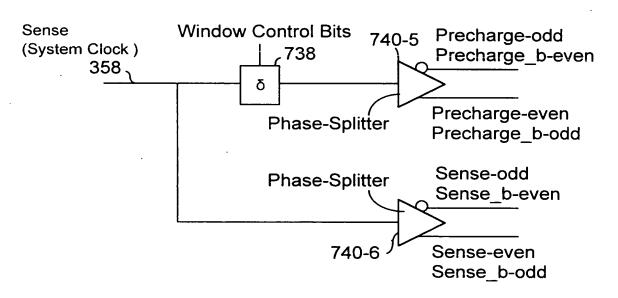


FIG. 17B



Timing Diagram of Precharge and Sense Signals FIG. 17C



Circuit for Timing Diagram of Fig.17C FIG. 17D

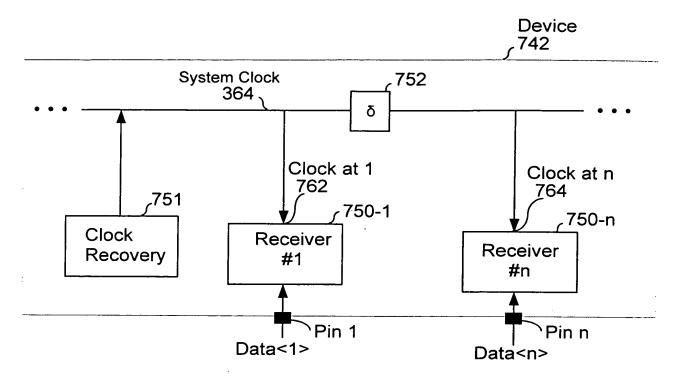
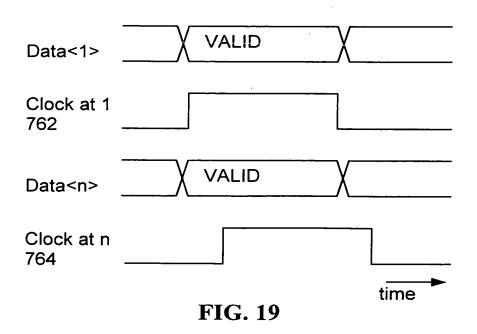


FIG. 18



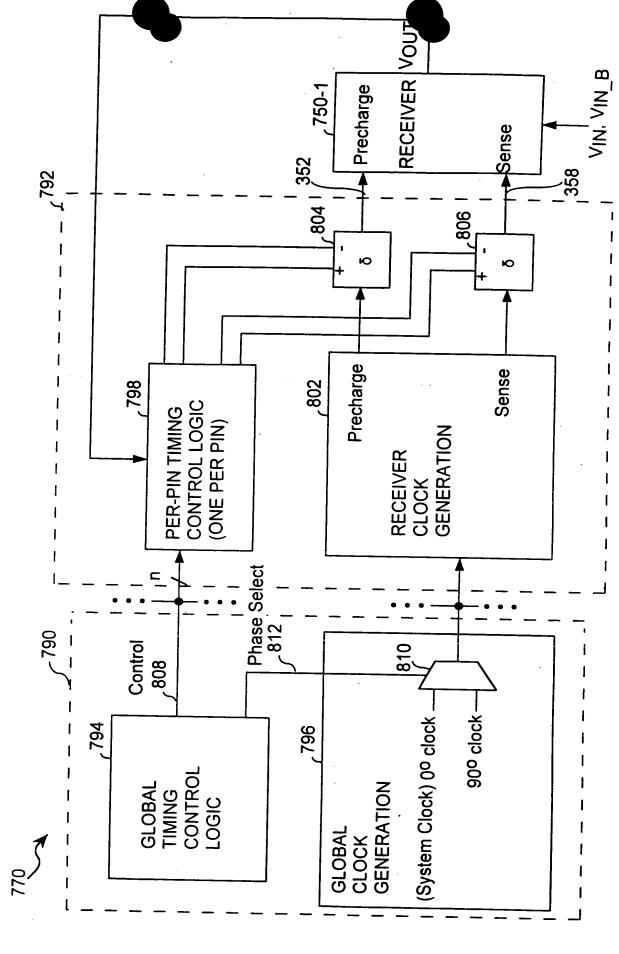
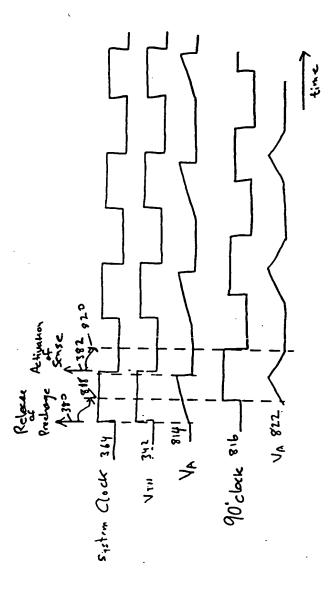
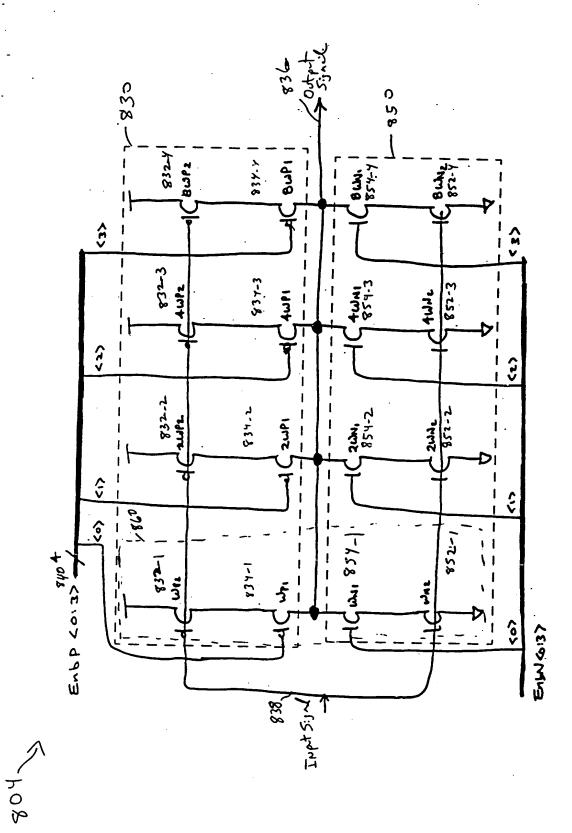


FIG. 20

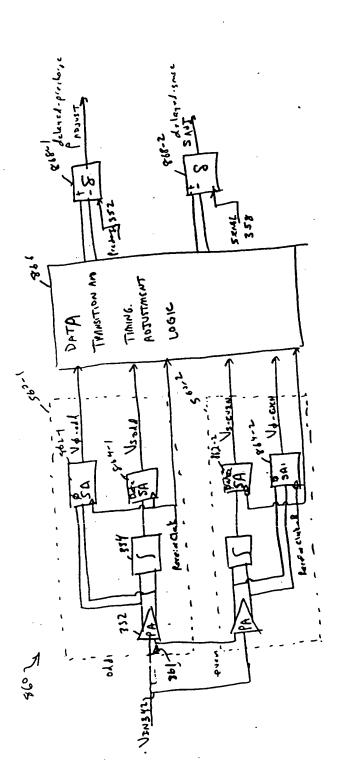


F16.2



F16.22

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F16 23 A

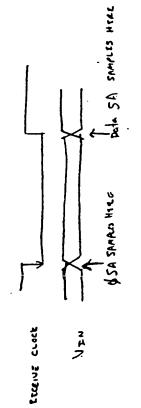
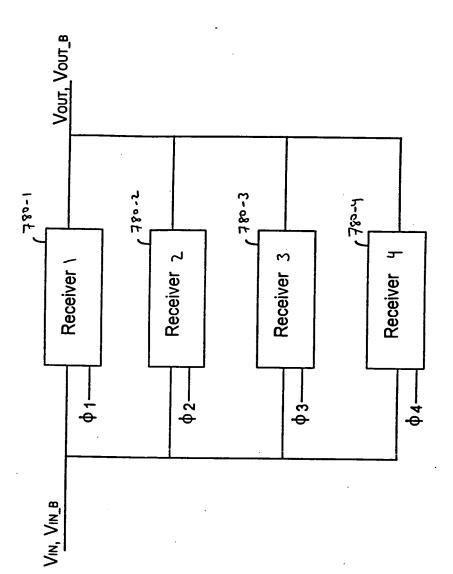
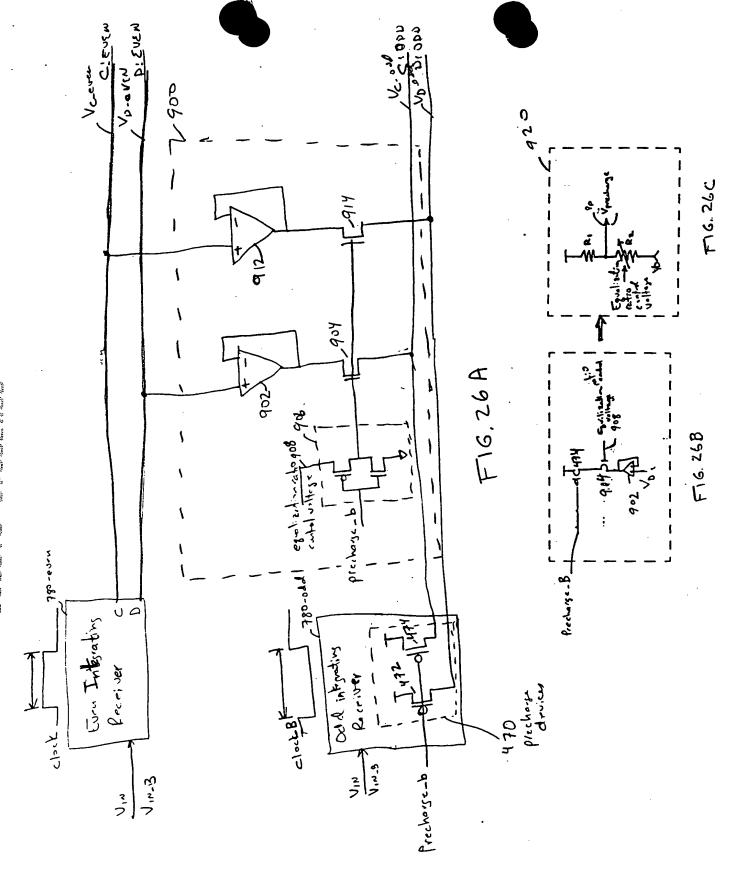


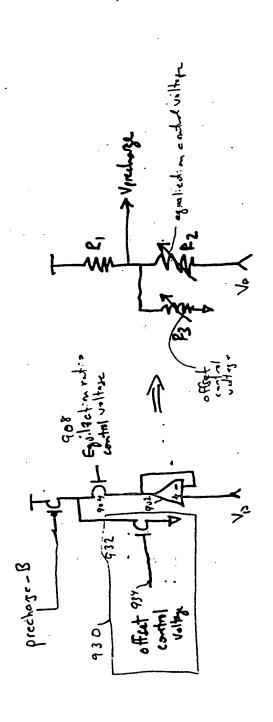
FIG. 23 B



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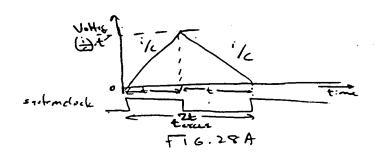
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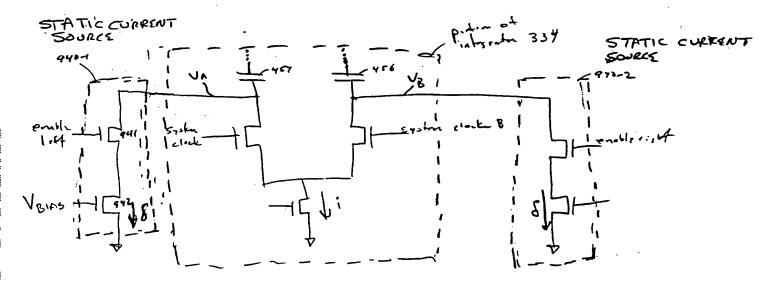




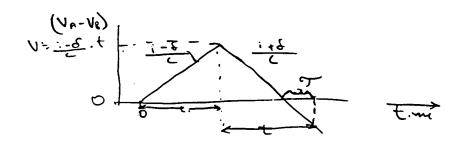
P 16

F16.27A





F16. 28B



F16, 28 C

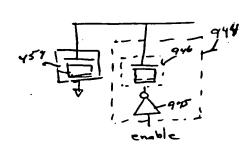


FIG. 28D

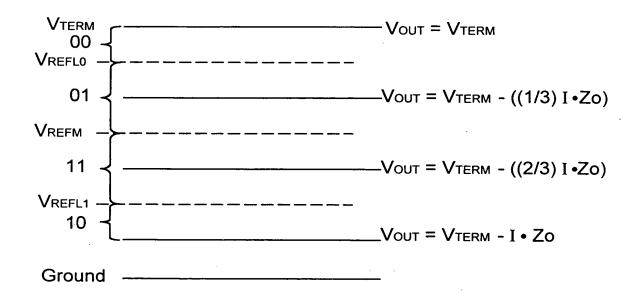
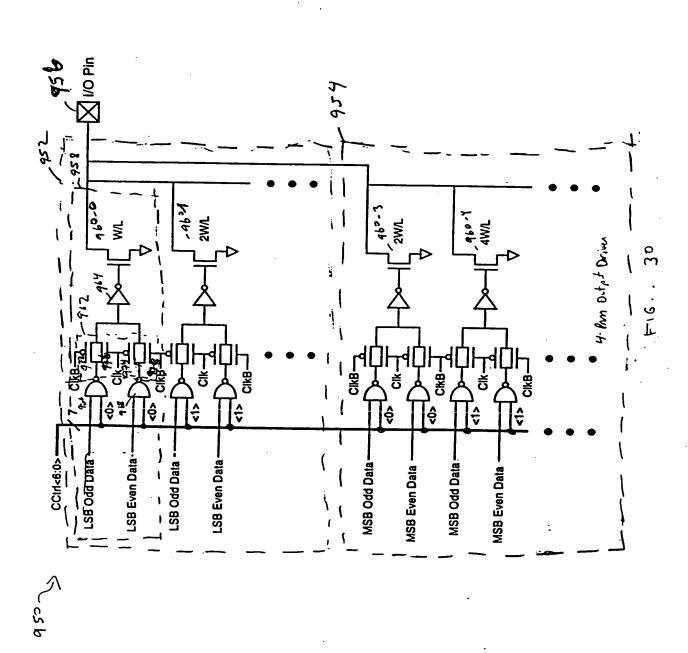
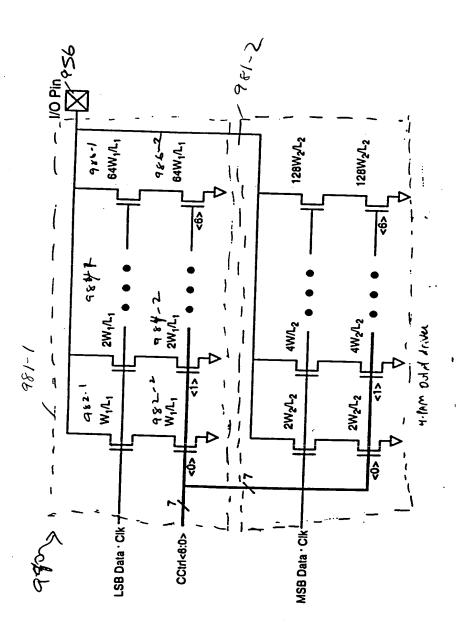
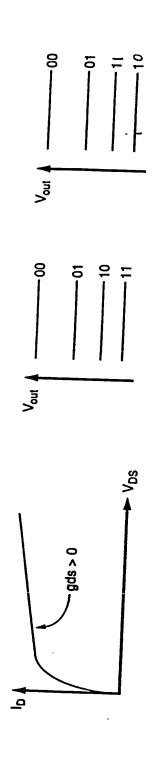


FIG. 29





F16.3



F16. 32C

FIG. 32B

F16.32A

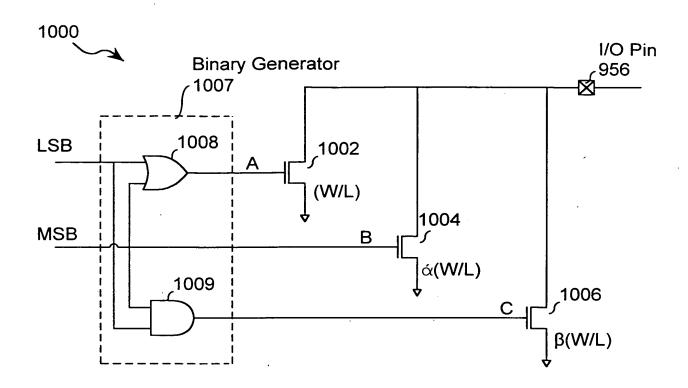
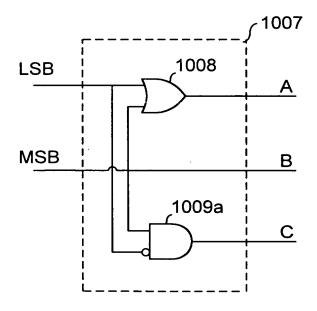
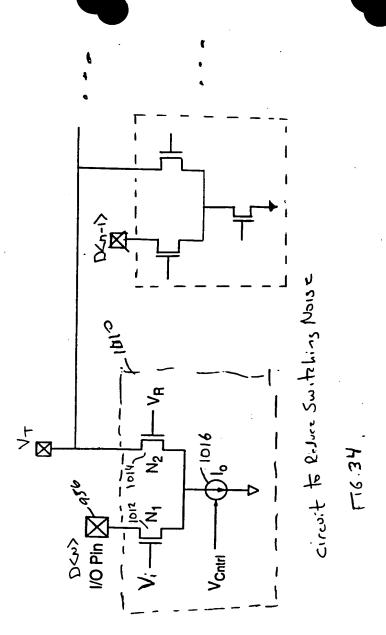


FIG. 33A



Gray Code Generator FIG. 33B



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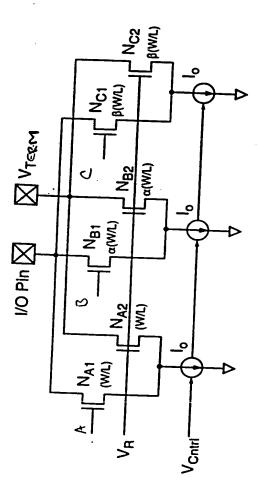
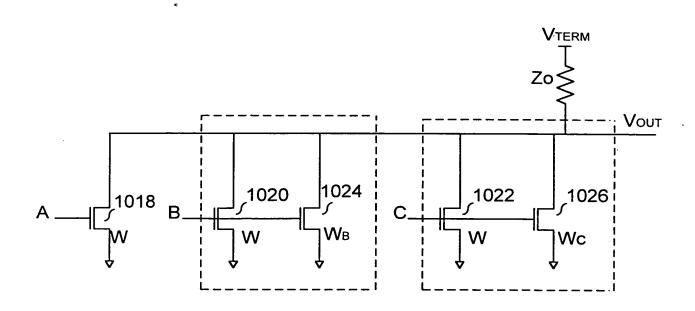
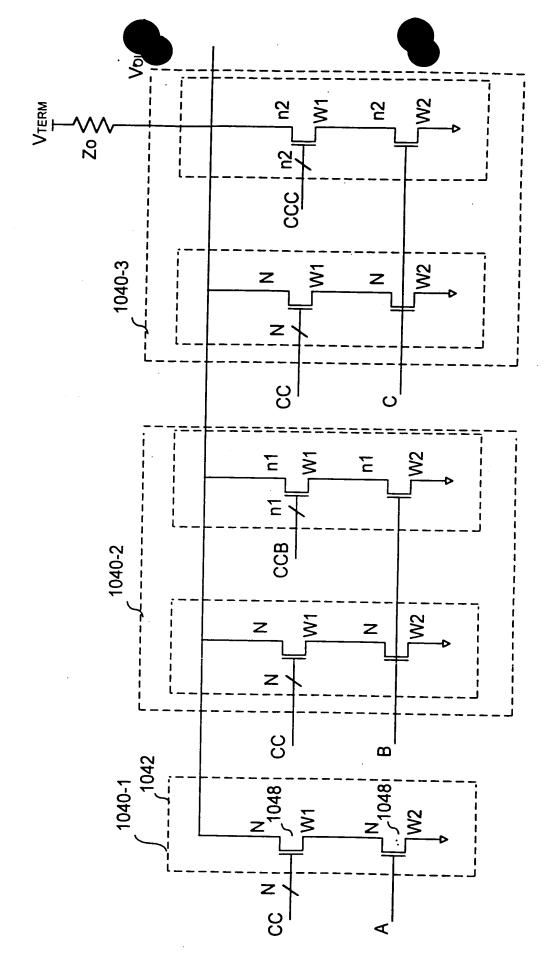


FIG 33



GDS Compensated Multi-PAM Output Driver ${f FIG.~36}$



GDS Compensated Multi-PAM Output Driver with Current Control ${
m FIG.\,37A}$

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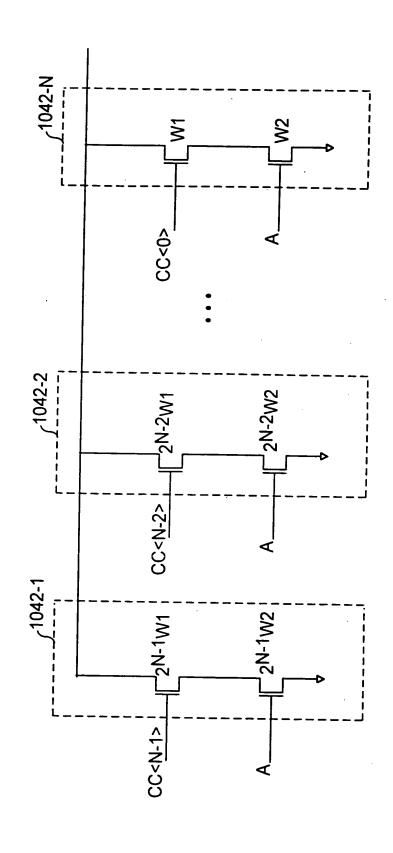
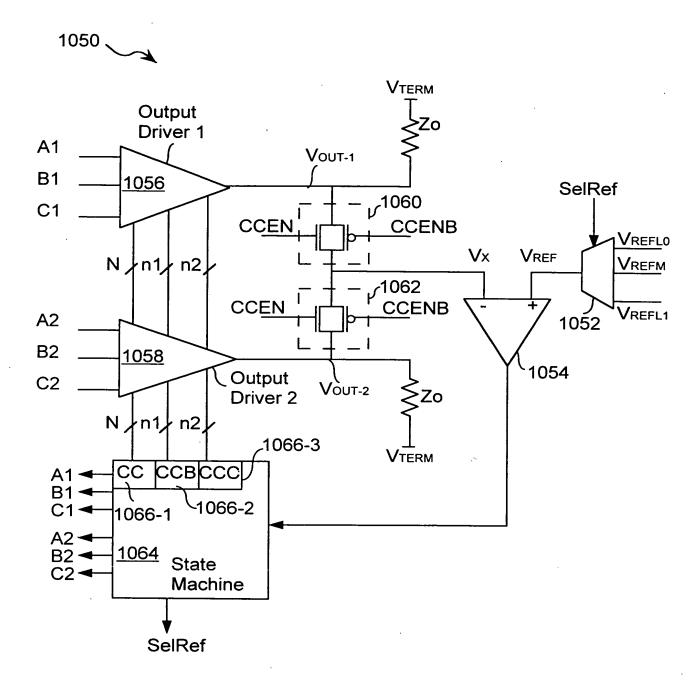


FIG. 37B



Circuit for Calibrating the GDS Compensated Output Driver with Current Control

FIG. 38

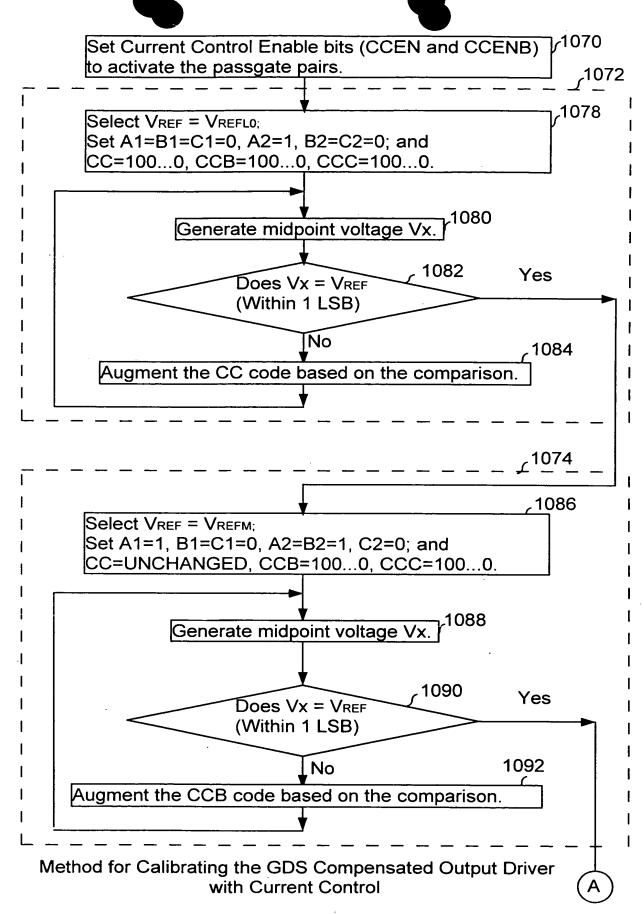
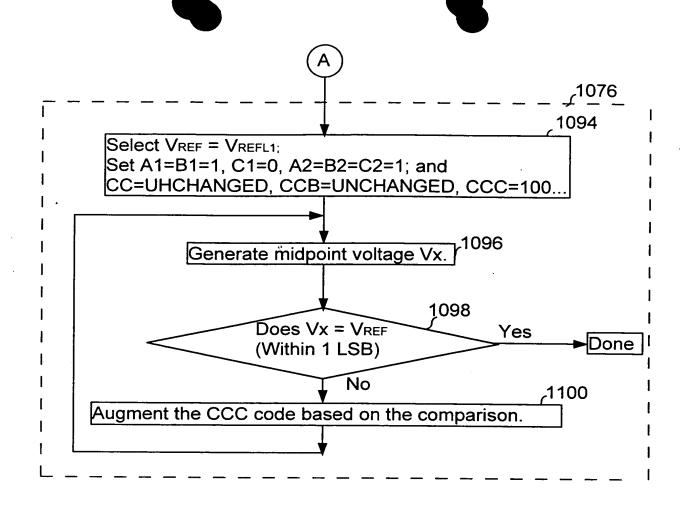


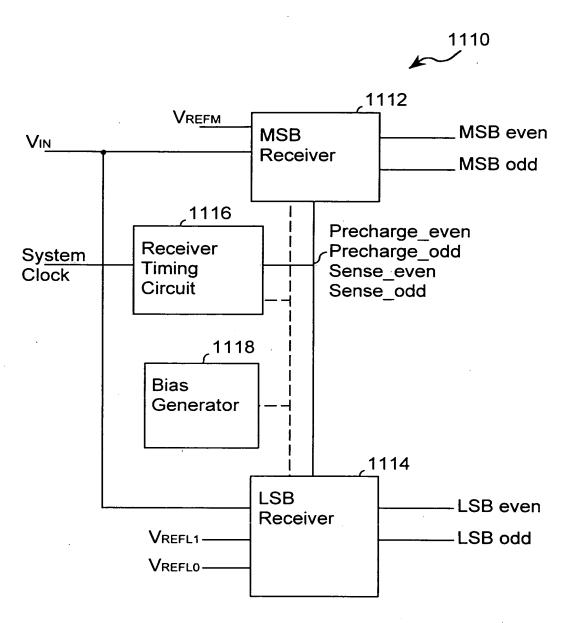
FIG. 39A



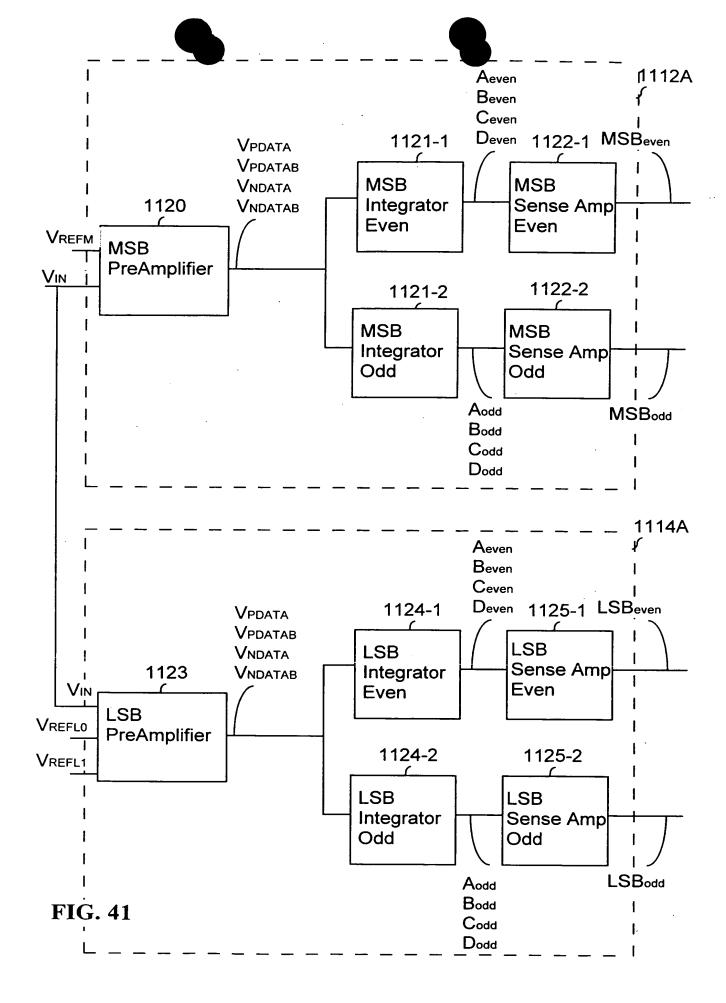
Method for Calibrating the GDS Compensated Output Driver with Current Control

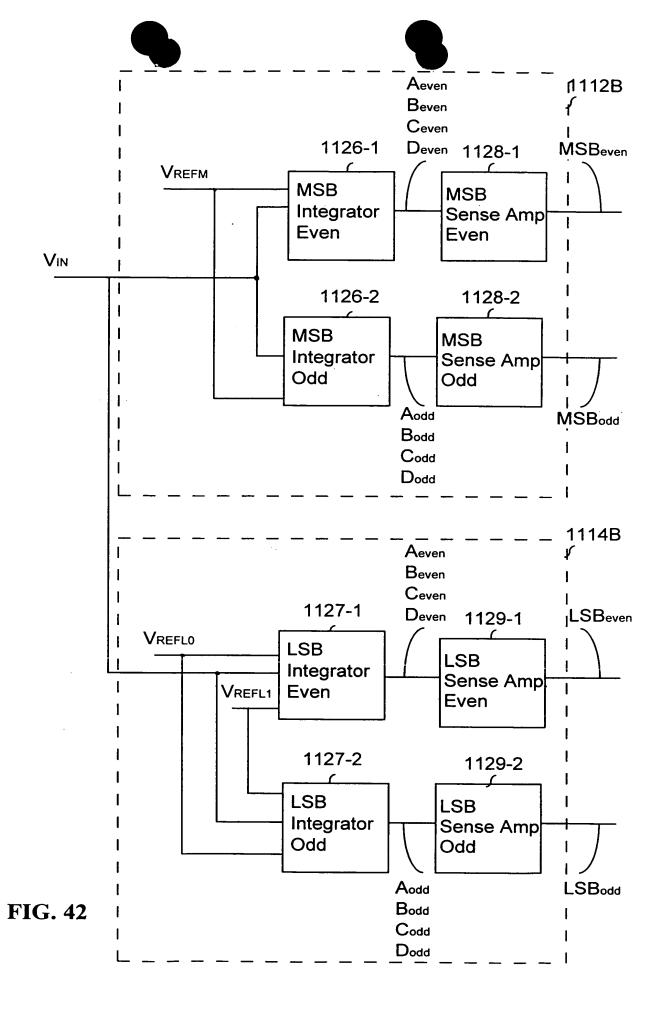
FIG. 39B

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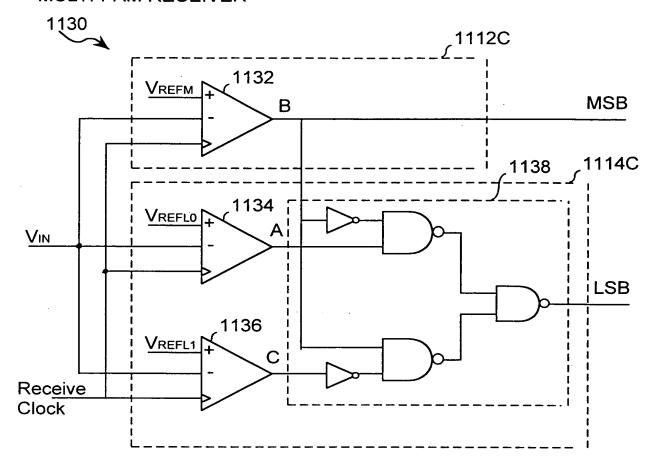


Multi-PAM Receiver FIG. 40

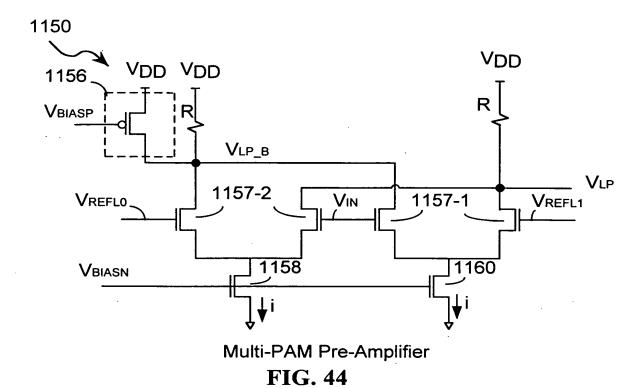


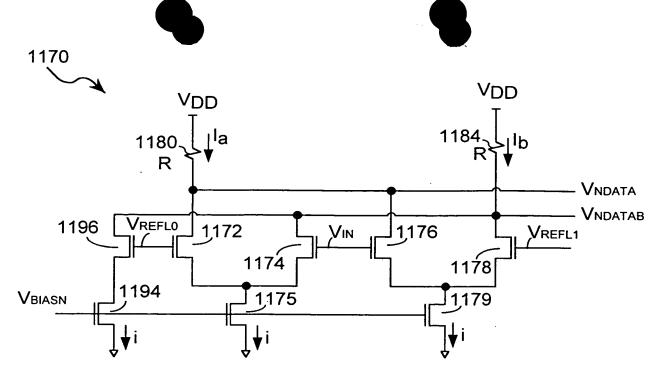




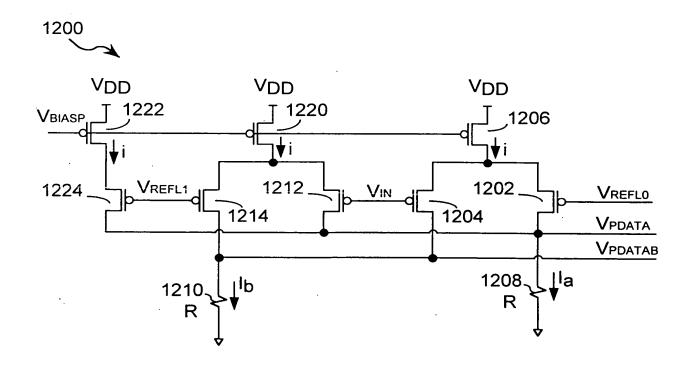


Multi-PAM Receiver FIG. 43

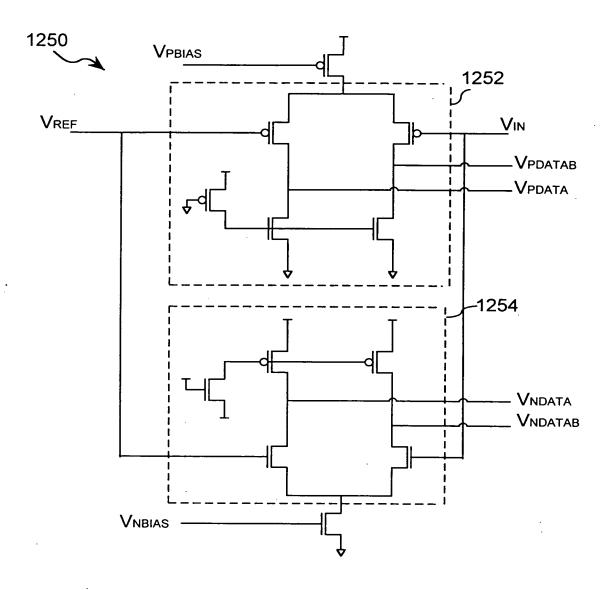




Multi-PAM Pre-Amplifier FIG. 45A



Multi-PAM Pre-Amplifier FIG. 45B



Multi-PAM Pre-Amplifier for MSB FIG. 46

LSB FOLDED INTEGRATOR

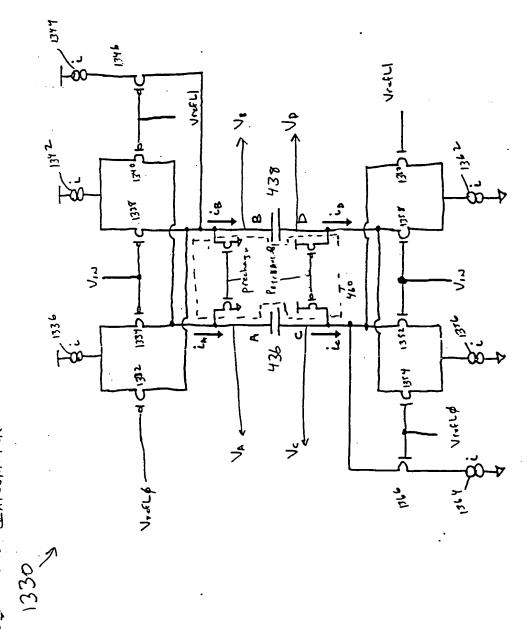


FIG. 47

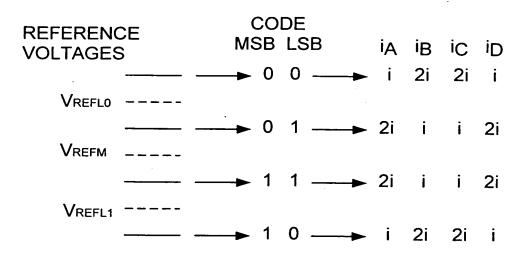


FIG. 48

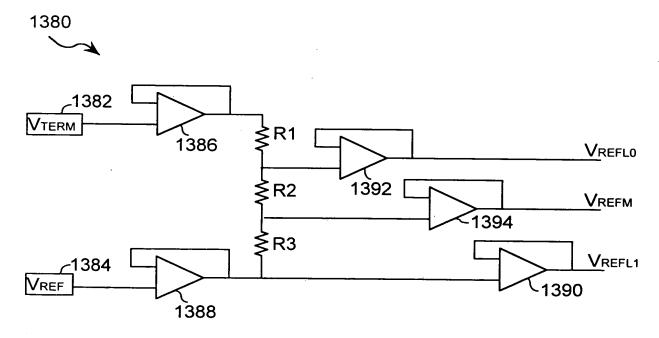


FIG. 49



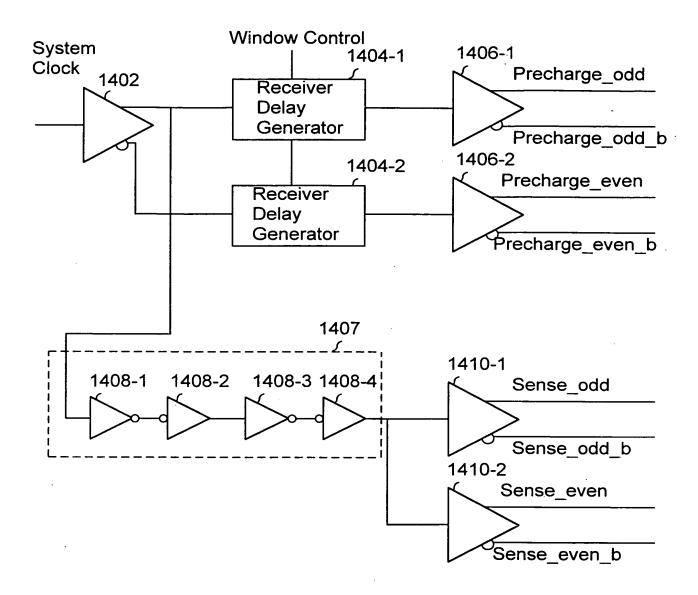
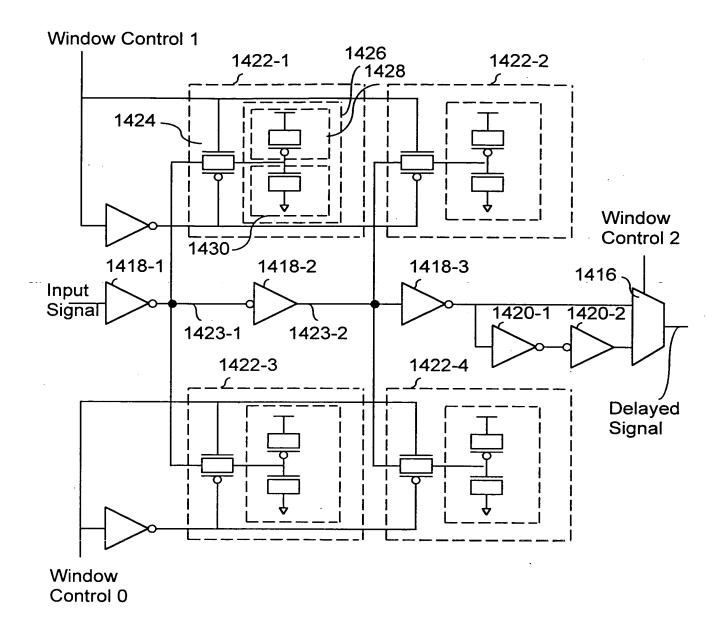


FIG. 50





Receiver Delay Generator

FIG. 51

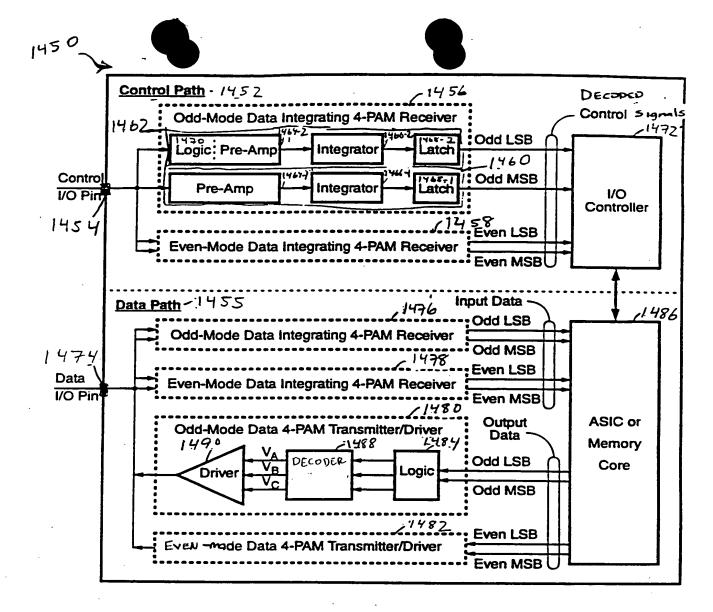


FIG. 52A

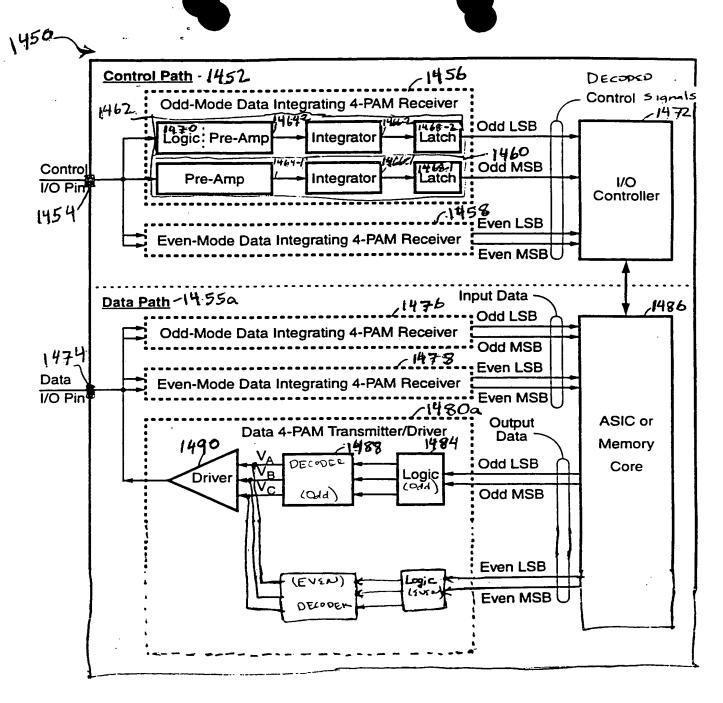
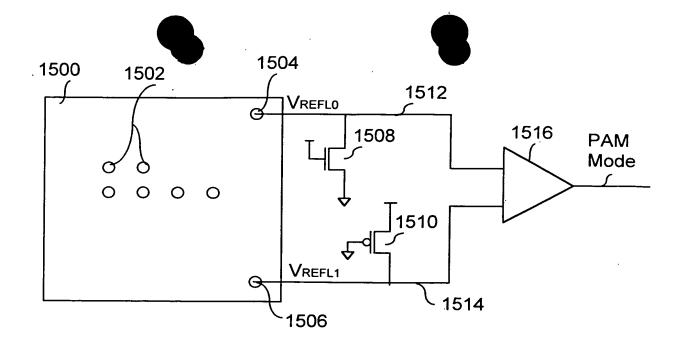
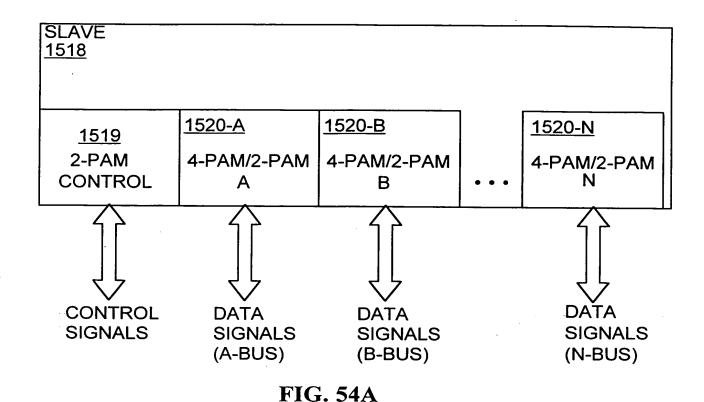
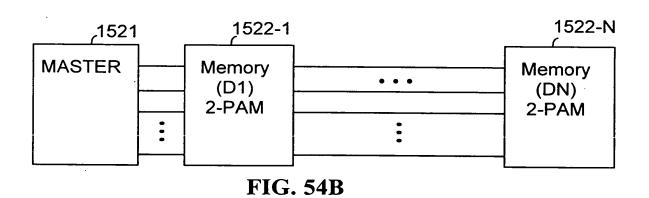


FIG. 52B



Automatic Detection of 2-PAM or 4-PAM Mode FIG. 53





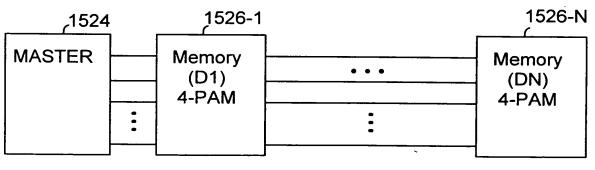


FIG. 54C

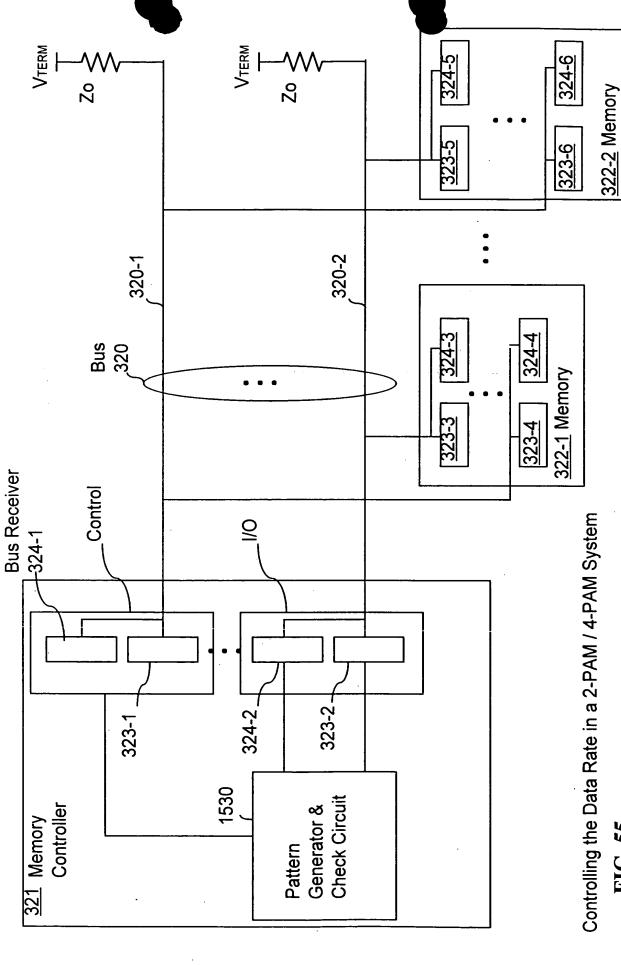
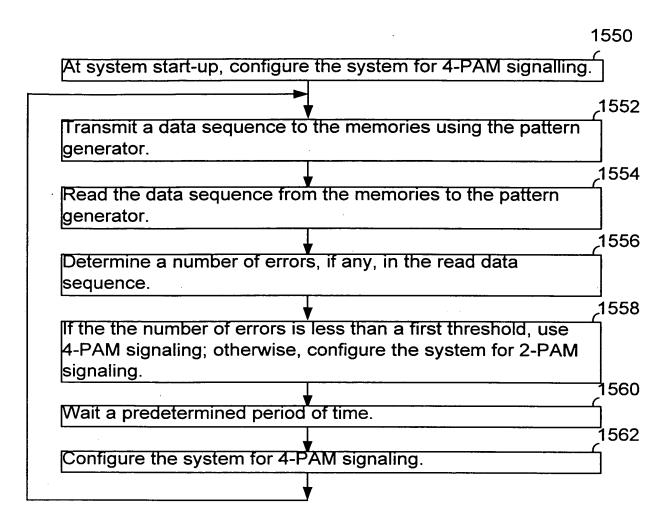
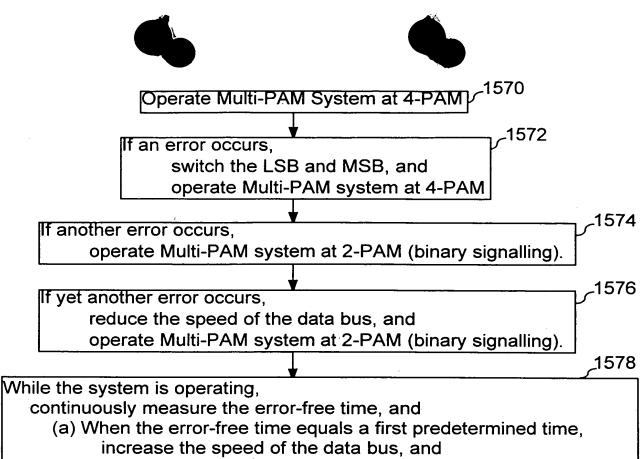


FIG. 55



Method for Determining 4-PAM / 2-PAM Signalling as a Function of Error Rate

FIG. 56



- operate the Multi-PAM System at 2-PAM (binary signalling);
- (b) Repeatedly: when the error-free time equals a second predetermined time.

increase the speed of the data bus, and continue to operate the Multi-PAM System at 2-PAM (binary signalling); and

increment the second predetermined time until the second predetermined time equals a PAM threshold value; and

(c) When the error-free time equals the PAM threshold value, operate the Multi-PAM System at 4-PAM.

FIG. 57

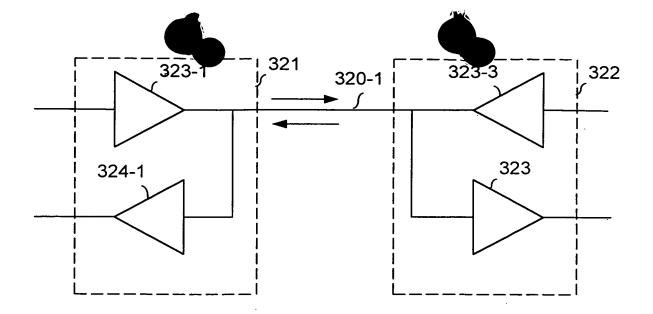


FIG. 58

